

Formulae Sheet for Fluid Dynamics

Cartesian coordinates

pressure, p , velocity, $\mathbf{u} = u\mathbf{e}_x + v\mathbf{e}_y + w\mathbf{e}_z$,

$$\begin{aligned} \nabla p &= \frac{\partial p}{\partial x}\mathbf{e}_x + \frac{\partial p}{\partial y}\mathbf{e}_y + \frac{\partial p}{\partial z}\mathbf{e}_z, & \nabla \cdot \mathbf{u} &= \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}, \\ \nabla \times \mathbf{u} &= \begin{pmatrix} \frac{\partial w}{\partial y} - \frac{\partial v}{\partial z} \\ \frac{\partial u}{\partial z} - \frac{\partial w}{\partial x} \\ \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \end{pmatrix} & \mathbf{u} \cdot \nabla \mathbf{u} &= \begin{pmatrix} u\frac{\partial u}{\partial x} + v\frac{\partial u}{\partial y} + w\frac{\partial u}{\partial z} \\ u\frac{\partial v}{\partial x} + v\frac{\partial v}{\partial y} + w\frac{\partial v}{\partial z} \\ u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} + w\frac{\partial w}{\partial z} \end{pmatrix} \\ \nabla^2 p &= \frac{\partial^2 p}{\partial x^2} + \frac{\partial^2 p}{\partial y^2} + \frac{\partial^2 p}{\partial z^2} & \nabla^2 \mathbf{u} &= \begin{pmatrix} \nabla^2 u \\ \nabla^2 v \\ \nabla^2 w \end{pmatrix} \end{aligned}$$

Cylindrical Polar Coordinates

velocity, $\mathbf{u} = u\mathbf{e}_r + v\mathbf{e}_\theta + w\mathbf{e}_z$.

$$\begin{aligned} \nabla p &= \frac{\partial p}{\partial r}\mathbf{e}_r + \frac{1}{r}\frac{\partial p}{\partial \theta}\mathbf{e}_\theta + \frac{\partial p}{\partial z}\mathbf{e}_z, & \nabla \cdot \mathbf{u} &= \frac{1}{r}\frac{\partial}{\partial r}(ru) + \frac{1}{r}\frac{\partial v}{\partial \theta} + \frac{\partial w}{\partial z}, \\ \nabla \times \mathbf{u} &= \begin{pmatrix} \frac{1}{r}\frac{\partial w}{\partial \theta} - \frac{\partial v}{\partial z} \\ \frac{\partial u}{\partial z} - \frac{\partial w}{\partial r} \\ \frac{1}{r}\frac{\partial}{\partial r}(rv) - \frac{1}{r}\frac{\partial u}{\partial \theta} \end{pmatrix} & \mathbf{u} \cdot \nabla \mathbf{u} &= \begin{pmatrix} u\frac{\partial u}{\partial r} + \frac{v}{r}\frac{\partial u}{\partial \theta} + w\frac{\partial u}{\partial z} - \frac{v^2}{r} \\ u\frac{\partial v}{\partial r} + \frac{v}{r}\frac{\partial v}{\partial \theta} + w\frac{\partial v}{\partial z} + \frac{uv}{r} \\ u\frac{\partial w}{\partial r} + \frac{v}{r}\frac{\partial w}{\partial \theta} + w\frac{\partial w}{\partial z} \end{pmatrix} \end{aligned}$$

$$\nabla^2 p = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial p}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 p}{\partial \theta^2} + \frac{\partial^2 p}{\partial z^2} \quad \nabla^2 \mathbf{u} = \begin{pmatrix} \nabla^2 u - \frac{2}{r^2} \frac{\partial v}{\partial \theta} - \frac{u}{r^2} \\ \nabla^2 v + \frac{2}{r^2} \frac{\partial u}{\partial \theta} - \frac{v}{r^2} \\ \nabla^2 w \end{pmatrix}$$

Spherical Polar Coordinates

$$\mathbf{u} = u\mathbf{e}_r + v\mathbf{e}_\theta + w\mathbf{e}_\phi$$

$$\nabla p = \frac{\partial p}{\partial r} \mathbf{e}_r + \frac{1}{r} \frac{\partial p}{\partial \theta} \mathbf{e}_\theta + \frac{1}{r \sin \theta} \frac{\partial p}{\partial \phi} \mathbf{e}_\phi,$$

$$\nabla \cdot \mathbf{u} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 u) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (v \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial w}{\partial \phi},$$

$$\nabla \times \mathbf{u} = \begin{pmatrix} \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (w \sin \theta) - \frac{1}{r} \frac{\partial v}{\partial \phi} \\ \frac{1}{r \sin \theta} \frac{\partial u}{\partial \phi} - \frac{1}{r} \frac{\partial}{\partial r} (rw) \\ \frac{1}{r} \frac{\partial}{\partial r} (rv) - \frac{1}{r} \frac{\partial u}{\partial \theta} \end{pmatrix}$$

$$\mathbf{u} \cdot \nabla \mathbf{u} = \begin{pmatrix} u \frac{\partial u}{\partial r} + \frac{v}{r} \frac{\partial u}{\partial \theta} + \frac{w}{r \sin \theta} \frac{\partial u}{\partial \phi} - \frac{v^2 + w^2}{r} \\ u \frac{\partial v}{\partial r} + \frac{v}{r} \frac{\partial v}{\partial \theta} + \frac{w}{r \sin \theta} \frac{\partial v}{\partial \phi} + \frac{uw}{r} - \frac{w^2 \cot \theta}{r} \\ u \frac{\partial w}{\partial r} + \frac{v}{r} \frac{\partial w}{\partial \theta} + \frac{w}{r \sin \theta} \frac{\partial w}{\partial \phi} + \frac{uw}{r} + \frac{vw \cot \theta}{r} \end{pmatrix}$$

$$\nabla^2 p = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial p}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial p}{\partial \theta} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial^2 p}{\partial \phi^2}$$

$$\nabla^2 \mathbf{u} = \begin{pmatrix} \nabla^2 u - \frac{2u}{r^2} - \frac{2}{r^2} \frac{\partial v}{\partial \theta} - \frac{2v \cot \theta}{r^2} - \frac{2}{r^2 \sin \theta} \frac{\partial w}{\partial \phi} \\ \nabla^2 v + \frac{2}{r^2} \frac{\partial u}{\partial \theta} - \frac{v}{r^2 \sin^2 \theta} - \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial w}{\partial \phi} \\ \nabla^2 w - \frac{w}{r^2 \sin^2 \theta} + \frac{2}{r^2 \sin \theta} \frac{\partial u}{\partial \phi} + \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial v}{\partial \phi} \end{pmatrix}$$